From Specification to Implementation: A Method for Designing Multi-Agent Systems in a Transformational Style

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ABSTRACT
The suitability of using the Chemical Reaction Metaphor (CRM) to model multi-agent systems (MASs) is justified by CRM’s capacity in specifying dynamic features of multi-agent systems. This paper presents a module language that facilitates a transformational method for implementing the specified multi-agent systems. A computation model with a tree-structured architecture is proposed to support the module language. The computational model is a straightforward abstraction of network operations in the context of coordination and transformation. Testing detailed, the multiset and network functionality pragmatizes the implementation of communications and synchronization among distributed agents. The transformational method is a rewriting process that translates the CRM specification into a program in the module language.

Keywords: Multi-agent systems, the chemical reaction models, program specification, very high-level languages, distributed systems, software architecture.

INTRODUCTION
Agent-oriented design has become one of the most active areas in the field of software engineering. The agent concept provides a focal point for accountability and responsibility for coping with the complexity of software systems both during design and execution (Yu, 2001). In this approach, a distributed system can be modeled as a set of autonomous, cooperating agents that communicate intelligently with one another, automate or semi-automate functional operations, and interact with human users at the right time with the right information. Such a model should be general enough to address common architectural issues and not be specific to design issues of a particular system.

The modeling issue in the abstract computing machine level has been studied in (Banatre, Fradet, & Radenac, 2004), where the chemical reaction model (Banatre & Le Metayer, 1990 & 1993, Banatre, Fradet, & Radenac 2005a, Le Metayer, 1990 & 1993) was introduced to program the computation. In the Gamma language, parallelism is left implicit and therefore a Gamma program is a true natural parallel program. The Gamma language was found suitable for describing a distributed and/or evolving system consisting of distributed entities that execute and interact with one another asynchronously and that are added into the system or deleted from the system dynamically. Follow-up researches revealed that the Gamma language can successfully address the architectural design issues since its computation model captures the dynamic characteristics of a distributed system (Inverardi & Wolf, 1995; Banatre & Le Metayer, 1996; Le Metayer, 1998). For instance, it is a distinguished language for the architectural design in coordination programming (Holzbacher, 1996), configuration programming (Kramer, 1990), and software architecture (Allen & Garlan, 1994; Garlan & Perry, 1995).

The basic term of a Gamma program is molecules (or γ-expressions), which can be simple data or programs (γ-abstractions). The execution of the Gamma program can be seen as the evolution of a solution of molecules, which react until the solution becomes inert. Molecules are recursively defined as constants, γ-abstractions, multisets or solution of molecules. The following is their syntax:

\[ M := 0 | 1 | \ldots | 'a' | 'b' | \ldots ; \text{ constants} \]
\[ \gamma P[C] M ; \gamma \text{-abstraction} \]
\[ M_1, M_2 ; \text{ multiset} \]
\[ <M> ; \text{ solution} \]

The multiset constructor “,” is associative and commutative (AC rule). Solutions encapsulate molecules. Molecules can move within solutions but not across solutions. γ-abstractions are elements of multisets, just like other elements. They can be applied to other elements of the same solution if a match to pattern \( P \) is found and condition \( C \) evaluates to true and therefore facilitate the chemical reaction. The pattern has the following syntax:

\[ P := x | P, P | <P> \]

where \( x \) is a variable. In addition, we allow for the use of tuples (written \( x_1, \ldots : x_n \) and names of types. For example, γ-abstraction

\[ \gamma(x: \text{Int}, y: \text{Int}) [x \geq y], x \]

becan interpreted as: replace \( x,y \) by \( x \) if \( x \geq y \), which is equivalent to finding the maximum of two integers.

The semantics of \( \gamma \)-Calculus is defined as the following:

\[ (\gamma P[C] M_1, M_2) = \phi M_1 \quad \text{if match}(P, M_2) = \phi \text{ and } \phi C \]
\[ \gamma \text{-conversion} \quad M_1, M_2 = M_2, M_1 \quad \text{commutativity} \]

The transformational method is a rewriting process that translates the CRM specification into a program in the module language. The presentation of our method will be in the following organization: In the second section, we present a brief description of the Chemical Reaction Metaphor; In the third section, we describe the proposed method for implementing CRM specifications of MASs. Discussions and Conclusions are drawn in the last section.
\[ m_r(m_2, m_3) = (m_r, m_3, m_2) \]
\[ E = E_0 \]

The \( \gamma \)-conversion describes the reaction mechanism. When the pattern \( p \) matches \( m \), a substitution \( \phi \) is yielded. If the condition \( \phi \) holds, the reactive molecules \( \gamma[p[c], m_1] \) and \( m_1 \) are consumed and a new molecule \( \gamma[m_1] \) is produced. \( \gamma[p/m] \) returns the substitution corresponding to the variable values if the matching succeeds, otherwise it returns \( \text{fail} \).

Chemical law formalizes the locality of reactions. \( E[E_t] \) denotes the molecule obtained by replacing holes in the context \( E_t \) (denoted by \( \{ \} \)) by the molecule \( E \). A molecule is said to be \( \text{inert} \) if no reaction can be made within:

\[ \text{Inert}(m) \Leftrightarrow (m = m'(\text{typ}[c].m_1, m_3) \Rightarrow \text{match}(p/m) = \text{fail}) \]

A solution is inert if all molecules within are inert and normal forms of chemical reactions are inert \( \gamma \)-expression. Elements inside a solution can be matched only if the solution is inert. Therefore, a pattern cannot match an active solution. This ensures that solutions cannot be decomposed before they reach their normal form and therefore permits the sequentialization of reactions. The following inference rule governs the evolution of \( \gamma \)-expressions:

\[
\frac{E_1 \rightarrow E_2}{E = C[E_1], E = C[E_2]} \quad \frac{E \rightarrow E'}{E_1 \rightarrow E'}
\]

For example, assume \( M, N, \) and \( R \) are names of three types, and \( f \) and \( g \) are two molecules that transform an element of \( M \) into an element of \( N \), and from \( N \) into \( R \), respectively, a producer can be defined as the following \( \gamma \)-abstraction:

\[ \text{prod} = \gamma(x: M)[\text{true}]. \langle f, g, x \rangle : N, \text{prod} \]

and a consumer can be defined as:

\[ \text{cons} = \gamma(x: N)[\text{true}]. \langle g, x \rangle : R, \text{cons} \]

A producer-consumer program that allows stream processing in which the producer and the consumer work concurrently can be written:

\[ \text{PC} M' = \langle M', \text{prod}, \text{cons} \rangle \]

where \( M' \) is the initial set of values of \( M \) type.

**IMPLEMENTING ARCHITECTURE SPECIFICATIONS**

Although there were discussions about implementing the Gamma language on parallel computers (Creveuil, 1991; Gladitz & Kuchen, 1996; Lin, Chen, & Wang, 1997), it is commonly accepted that there is no straight implementation of the Gamma language that is efficient. After all, the Gamma language was designed as a very high level language for program specifications and is, therefore, used to specify the architectures of the coordinating systems. In a sequel, node-specific software design in a distributed system still relies on conventional software engineering methods. In a distributed multi-agent system, the separation of architectural design and the design on proprietary platforms is obtained even more necessary for dealing with the complexity of the system (Lin, Lin, & Holt, 2003). Therefore, we will restrict the following discussion to implementing the Gamma specification of the multi-agent systems in the architectural level with a minimum assumption about the computation model supported by the underlying system.

**Computation Model**

The computation model on which we discuss the implementation of a Gamma specification is a multi-process system, with processes dynamically created and deleted and interacting with one another. No assumption is made about the allocation of the processes on distributed nodes of the underlying computing network. That is to say that multiple processes can run on a single node or on distributed nodes. The hierarchy of the multi-processes is a tree structure, in which processes have full control over the creation/deletion of their descendant processes in the lower level, but not vice versa. A process can “lock/unlock” its activities. Locking means the freeze of all local computations and unlocking is the reverse operation. However, locking/unlocking does not apply to communications between the manipulated processes and other nodes. Communications among nodes are performed through communication channels which support unicast and multicast communications. However, these communication functions are process based instead of IP address based. That is to say, for example, multicast involves a set of processes instead of a set of nodes with distinct IP addresses.

**Module Specification**

We propose a language for specifying processes that run on an execution environment that supports the above computation model. Processes are specified by modules in the module language. A module is composed of a name, a parameter list used to take initial data when the process starts running, and a body block consisting of sequentially executed statements.

```
module name(parameter-list)
begin
statement-sequence
end
```

First-class values are stored in a data pool named \( \text{pool(mid)} \), where \( \text{mid} \) is the name of the module. We leave the data structures of the data pool unspecified to maintain high-level abstraction. Their implementation is left to the stage of coding in a concrete programming language, which is subject to proprietary platform technologies. We do assume, however, that data items are addressed in the data pool so that we can locate particular data items and delete them.

Each module is associated with two multicast groups: \( \text{sync(mid)} \) and \( \text{dist(mid)} \). \( \text{sync(mid)} \) is the multicast group used to implement atomic captures of molecules. It involves synchronization using \( \text{syn} \) and \( \text{ack} \) messages, as described above. \( \text{dist(mid)} \) is the multicast group for distributing produced molecules. We use \( \text{mid} \) as an argument to identify the multicast group to which \( \text{mid} \) belongs, such as \( \text{sync(mid)} \) and \( \text{dist(mid)} \). We may use \( \text{sync} \) or \( \text{dist} \) along if there is no ambiguity. Note that both \( \text{sync} \) and \( \text{dist} \) can be either syntactically (statically) or semantically (dynamically) checked. The syntactic check is used in this paper. We will show how to do the syntactic check in Section 3.4.

Operations performed by a process include local operations, communications, and process control operations. There are four local operations that can be performed by a process:

- **Add(data)**: add data into the pool
- **Delete(data)**: delete data from pool
- **Select():** select a set of element in pool that may match the pattern. The set of selected elements is returned by the function if the selection is successful, or \( \text{fail} \) otherwise.
- **Release():** release the selected elements and return them to pool.

Two communication operations:

- **Send(type, sid, data)**: send a message. \( \text{type} \) can be \( \text{syn} \), \( \text{desyn} \), \( \text{ack} \), or \( \text{dis} \). Semantics of \( \text{Send} \) operation differs with different types. A \( \text{syn/desyn} \) message is sent to all processes in multicast group \( \text{sync/desyn} \), while an \( \text{ack} \) message is unicast to the sender of the \( \text{syn} \) message identified by \( \text{sid} \). In addition, \( \text{dist} \) and \( \text{ack} \) message is empty. A \( \text{dis} \) message is sent to all processes in multicast group \( \text{dist} \) and \( \text{sid} \) is insignificant.
- **Recv(type, sid, data)**: Probe the message queue, return the first message (through parameters \( \text{type} \), \( \text{sid} \), and \( \text{data} \)), or \( \text{fail} \) (through function return...
value) otherwise. The function can return data sent by multiple senders identified by ids, e.g., Recv(ack, sync, ) checks whether the sync message has been acknowledged by all processes in sync.

and five process control operations:

- **Create(id, arg1, arg2, …, argn)**: create a module with the given name and argument list. The argument list is used to pass initial data set to the created module.
- **Delete(id)**: delete the module whose id is specified in the parameter and collect the resulting multiset in pool of module id and join it with the local pool. Also, add id into the local pool. If module id is not inert, Delete(id) does not have effect and return immediately.
- **Inert()**: This is an overloaded operation. The default version (no argument) freezes local activities in the local module if no more actions can occur, and return true, or false otherwise; while the version with a module id (Inert(id)) tests whether module id is inert. Inert(id) function does not affect communications between the module and other modules. In addition, once a module is inert, a message is sent automatically to the solution module in the immediate upper level. If Inert(id) is called by a solution module, it automatically checks whether there are still active modules in the lower level by checking the received messages. A solution module will not become inert until all lower level modules are inert.
- **React()**: resume local activities in the local module. Also, once a module is re-activated, a message is sent automatically to the solution module in the immediate upper level.
- **Thread(abs, arg1, arg2, …, argn)**: create a thread, which runs the program represented by the abs parameter. This feature is used to support mobile agents, codes sent by other modules and run on the environment of the module that receives it. The mobile agent is run as a thread so that it shares the data in the execution environment of the receiving module. The result of the thread, if any, can be retrieved by <abs>.

The body block of a module consists of a sequence of statements separated by ".". A statement is either a call to the one of above operations, a conditional statement, or a looping statement. The following is the BNF definition:

```
block ::= begin statement-sequence end
statement-sequence ::= statement ; statement-sequence | empty
statement ::= operations | conditional | looping
conditional ::= if reacions \f
reactions ::= reaction ; reactions | empty
reaction ::= cond -> actions
cond ::= actions, bool-expression
actions ::= action , actions | empty
action ::= statement
looping ::= do reactions od
bool-expression ::= ... ; an expression returning either true or false
operations ::= ... ; the operations described above
```

The conditional statement has the following semantics: conditions are tested and one of the statements whose corresponding conditions test to true is executed. If none of the conditions test to true, the control falls through the if statement and continues to execute the statement that follows it. Its semantics of the looping statement is: in each iteration, conditions are tested and one of the statements whose corresponding conditions test to true is executed. This process is repeated until none of the conditions evaluates to true. This semantics of the conditional and looping statements is non-deterministic since no rule is set to govern how to select the statement to execute when multiple conditions are evaluated to true.

Note that even the module language is still a high level specification language, e.g., it leaves data structures and underlying communication mechanisms unspecified and has nondeterministic control structures, it is a language based on the realistic computation model. No higher-order operations exist in a program in the module language.

For example, the three modules designed for the producer-consumer problem are in the following. PC is the solution module, which creates the producer module (prod) and consumer module (cons). In this particular program, sync is empty because the patterns of prod and cons do not intersect. Dist(prod) = {cons} and Dist(cons) = ∅, which means that the produced molecules are sent from prod to cons but not vice versa.

```
module PC(M)
begin
  Create(prod, M); Create(cons);
  do
    Inert() -> ; polling the status of both prod and cons
  od
  Delete(prod); Delete(cons)
end
```

The modules designed for the nth element program follow.

```
module nth(M, n)
begin
  Create(sigma, M);
  do
    Inert(sigma) -> Delete(sigma), Create(extr, pool, n);
  od
  Delete(extr);
end
```

```
module sigm(M)
begin
  do
    (i, a): M, (b, j): M = Select() and i < j and a > b
    -> Delete((i, a): M, (b, j): M), Add((b, i): M, (a, j): M);
  od
end
```

The above module specifications have artificial simplifications that make them different from the module specifications obtained in an automatic transformation (depicted in Section 3.4). For example, in a reaction, there should be a test whether the sync group is empty before replacing elements. If the sync group is not empty, a sync message must be sent and acknowledged before performing the replacement. Similarly, after the reaction, there should be a test to the dist group.

By removing higher-order operations in the module level, we make the specification of the system closer to actual program. Implementation of the program in the module language can be carried out fairly directly on a system that supports the computation model of the module language. Note that the implementation of
local computations is out of the scope of this paper. It is left to the phase when the use of concrete language and platform are determined. We will rely on software engineering technologies for finding an efficient implementation of local computations. For example, further refinement of the specification should include the use of data structures to organize the data sets and implement the Select operation by an algorithm designed in accordance with the data structure.

We refer the readers to (Lin, 2006) for case studies of the proposed method. (Lin, 2006) uses a higher-order Gamma formalism proposed by Le Metayer (1994). More current studies including case studies and applications in Gamma Calculus is being prepared for publication in the near future.

DISCUSSIONS AND CONCLUDING REMARKS

The chemical reaction models were proposed years ago to address high-level design issues of large distributed systems. Our work shows that it can be used to design multi-agent systems in a top-down fashion and benefits the design methodology with the reasoning capability of a formal system. While have shown that implementing such a system is feasible on a network computing environment, we would like to point out that our method can only be exerted to the module level, i.e., we can only derive the system to the specifications of module interfaces and operations. The implementation of individual modules will rely on conventional software engineering technologies. Further studies are needed to address the issues concerning module implementation and, perhaps, module abstraction, if we are to follow a “bottom-up” approach to design the multi-agent system, i.e., build the system on top of a set of existing functional units that coordinate over networks.

We present a method for implementing multi-agent system specifications in Gamma Calculus using a transformational style. Our existing work has demonstrated that Gamma Calculus, the newest formalism of the chemical reaction models, is suitable to describe high-level architectural properties of multi-agent systems and allows for systematic derivation and implementation of the systems. In this paper, we present a set of rules that can be used to derive the specified system into a module language, which is an intermediate language that do not include any higher-order operations as those in Gamma Calculus and is supported by most common networking execution environment. This study paves the way for implementing the specified system by using a sequence of program transformation and offers a new method for multi-agent system design.

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